

1 Review

1.1 Fundamental equations

Advection diffusion, concentration C

$$\frac{DC}{Dt} = \frac{\partial C}{\partial t} + u_i \frac{\partial C}{\partial x_i} = D \frac{\partial^2 C}{\partial x_i \partial x_I} \quad (1.1)$$

Mass conservation (continuity)

$$\frac{D\rho}{Dt} + \rho \frac{\partial u_i}{\partial x_i} = 0 \quad (1.2)$$

if ρ is nearly constant, we get incompressible continuity equation.

$$\frac{1}{\rho} \frac{D\rho}{Dt} \ll \frac{\partial u_1}{\partial x_1}, \frac{\partial u_2}{\partial x_2}, \frac{\partial u_3}{\partial x_3} \Rightarrow \frac{\partial u_i}{\partial x_i} = 0 \quad (1.3)$$

Navier-Stokes(momentum) equations

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \nu \nabla^2 u_i + g_i \quad (1.4)$$

this is for fixed reference frame (inertial) and incompressible, ρ and ν are constant. The terms on the *rhs* are pressure, viscous stress and weight. $\mathbf{g} = (0, 0, -g)$ or only $g_3 = -g$.

On the Vertical direction, i.e., $i = 3$, $g_i = -g$, we write the equation like following.

$$\frac{\partial u_3}{\partial t} + u_j \frac{\partial u_3}{\partial x_j} - \nu \nabla^2 u_3 = -\frac{1}{\rho} \frac{\partial p}{\partial x_3} - g \quad (1.5)$$

the *rhs* represent hydrostatic relevance. if the 3 terms on *lhs* are **individually** $\ll g$, that is,

$$\frac{\partial u_3}{\partial t} \ll g \quad \text{and} \quad u_j \frac{\partial u_3}{\partial x_j} \ll g \quad \text{and} \quad \nu \nabla^2 u_3 \ll g \quad (1.6)$$

then we can get hydrostatic approximation

$$\frac{\partial p}{\partial x_3} = -\rho g \quad (1.7)$$

\ll the other term on *rhs* is also ok, but that term is responding to g , and g is fixed(easy to compare). if $u_3 = 0$, then hydrostatic approximation is exactly valid.

1.2 Density variations in the environment

the density varies $\rho = \rho(x_1, x_2, x_3, t)$. this is in response to temperature (for water or air), salinity (for water), pressure (for air). We will focus on the first two, so $\rho = \rho(S, T)$. For fresh water, $\rho = 1000 \text{ kg/m}^3$. For sea water, $\rho \approx 1030 \text{ kg/m}^3$.

We can decompose varying density to background constant density and fluctuations. $\bar{\rho}, \rho' \ll \rho_0$ and $\rho_0 = 1000 \text{ kg/m}^3$. $\bar{\rho}(x_3)$ represent stable vertical density stratification.

$$\rho(x_1, x_2, x_3, t) = \rho_0 + \bar{\rho}(x_3) + \rho'(x_1, x_2, x_3, t) = \rho_0 + \tilde{\rho} \quad (1.8)$$

Boussinesq Approximation, if $\rho = \rho_0 + \tilde{\rho}$ and $\tilde{\rho} \ll \rho_0$ so we can neglect some terms. e.g., in continuity equation with variable density would be

$$\frac{1}{\rho} \frac{D\rho}{Dt} + \frac{\partial u_i}{\partial x_i} = 0 \quad (1.9)$$

using $\rho = \rho_0 + \tilde{\rho}$, then we left just $\tilde{\rho}$, getting

$$\frac{1}{\rho_0 + \tilde{\rho}} \frac{D\tilde{\rho}}{Dt} + \frac{\partial u_i}{\partial x_i} = 0 \quad (1.10)$$

And as $\tilde{\rho} \ll \rho_0$, the denominator becomes ρ_0 .

$$\frac{1}{\rho_0} \frac{D\tilde{\rho}}{Dt} + \frac{\partial u_i}{\partial x_i} = 0 \quad (1.11)$$

momentum equations for density not constant:

$$\rho \frac{\partial u_i}{\partial t} + \rho u_j \frac{\partial u_i}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \mu \nabla^2 u_i + \rho g_i \quad (1.12)$$

also use $\rho = \rho_0 + \tilde{\rho}$ and assume $\tilde{\rho} \ll \rho_0$, dividing all term by ρ_0 , we get

$$\frac{\rho_0 + \tilde{\rho}}{\rho_0} \frac{D u_i}{Dt} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x_i} + \frac{\mu}{\rho_0} \nabla^2 u_i + \frac{\rho_0 + \tilde{\rho}}{\rho_0} g_i \quad (1.13)$$

leading to

$$\frac{D u_i}{Dt} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x_i} + \nu \nabla^2 u_i + g_i + \frac{\tilde{\rho}}{\rho_0} g_i \quad (1.14)$$

it shows that what density variation may cause effect is the last term. note g_i is balanced by hydrostatic approximation, and the last gravity term may affect *lhs* as well as vertical movement. we call the last term reduced gravity $g' = g\tilde{\rho}/\rho_0$ or buoyancy forcing.

Further explanation on balance

For further explanation, separate pressure into hydrostatic and dynamic components $p = p_H + p_D$, then

$$\frac{D u_3}{Dt} = -\frac{1}{\rho_0} \frac{\partial p_H}{\partial x_3} - \frac{1}{\rho_0} \frac{\partial p_D}{\partial x_3} + \nu \nabla^2 u_3 - g - \frac{\tilde{\rho}}{\rho_0} g \quad (1.15)$$

we say the balance may be

$$\frac{\partial p_H}{\partial x_3} = -\rho g \quad (1.16)$$

the remaining is

$$\frac{D u_3}{Dt} = -\frac{1}{\rho_0} \frac{\partial p_D}{\partial x_3} + \nu \nabla^2 u_3 - \frac{\tilde{\rho}}{\rho_0} g \quad (1.17)$$

and we can not say which term is bigger or smaller in the equation above.

Question 1:

What if $\frac{D u_3}{Dt}$ is of nearly the same magnitude with g ? Should it be put into (16)?

ans: p_D will respond.

1.3 Vertical density-based motions

Assuming density linearly increases with depth. We will get $\frac{\partial \rho}{\partial z} < 0$ is stable while $\frac{\partial \rho}{\partial z} > 0$ is unstable.

Take a small parcel of fluid, and write its equation, that is

$$\frac{\partial}{\partial t}(\rho_0 w) = -g\Delta\rho \quad (1.18)$$

while $w = \frac{\partial z}{\partial t}$ where z is position of parcel. $\Delta\rho = -\frac{\partial\rho}{\partial z}\Delta z$. so we get

we choose at the stable point $z = 0$ so $\Delta z = z$

$$\rho_0 \frac{\partial^2 z}{\partial t^2} = g \frac{\partial \rho}{\partial z} z \Rightarrow \frac{d^2 z}{dt^2} = \left(\frac{g}{\rho_0} \frac{\partial \rho}{\partial z} \right) z \quad (1.19)$$

the term in the bracket is constant, we assign it $-N^2$, called Brunt-Väisälä Frequency. For $\frac{\partial \rho}{\partial z} < 0$, we will get $N^2 > 0$, and we get sin and cos solutions. The oscillatory period is $2\pi/N$.

$$\frac{d^2 z}{dt^2} + N^2 z = 0 \Rightarrow z = A \cos(Nt) + B \sin(Nt) \quad (1.20)$$

For $\frac{\partial \rho}{\partial z} > 0$, we get exponentials.

$$z = A e^{Nt} + B e^{-Nt} \quad (1.21)$$

so this is unstable. The abs of $\frac{\partial \rho}{\partial z}$ measures the strength of stratification and N . bigger N leads faster oscillation.

1.4 Long Box problem, Coastal Estuary

Now we think about **horizontal stratification**. River flows into ocean. In river, the salinity is zero. In ocean, the salinity is 35 ppt. Tides, winds affects. and we get salinity gradient. Set $S = S(x)$ and $\rho = \rho(x)$, depth $H(x)$. Dynamics for u_1 is

$$\frac{\partial u_1}{\partial t} + u_j \frac{\partial u_1}{\partial x_j} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x_1} + \nu \frac{\partial^2 u_1}{\partial x_j \partial x_j} \quad (1.22)$$

And $v = 0$, and because large-scale horizontal flow, $w \rightarrow 0$, also horizontal scale is very large so $\frac{\partial u}{\partial x} \rightarrow 0$. For inviscid solution also no ν term. so

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} \quad (1.23)$$

so $\frac{\partial p}{\partial x}$ is crucial in controlling flow. we want to derive $\frac{\partial p}{\partial x}$. Assuming $u_3 = 0$, flat bottom $z = 0$, with hydrostatic approximation [Equation 1.7](#),

$$p(x, z) = p_{\text{atm}} + \rho(x)g(H - z) \quad (1.24)$$

then

$$\frac{\partial p}{\partial x} = \frac{\partial}{\partial x} [p_{\text{atm}} + \rho g(H - z)] = \rho g \frac{\partial H}{\partial x} + g \frac{\partial \rho}{\partial x} (H - z) \quad (1.25)$$

$$\frac{\partial u}{\partial t} = -g \frac{\partial H}{\partial x} - \frac{g}{\rho_0} \frac{\partial \rho}{\partial x} (H - z) \quad (1.26)$$

the first term is barotropic like tides, river flow, etc., meaning the density and pressure together varies in the vertical direction. The second term is baroclinic, density driven flow or say exchange flow. The density and pressure varies in different direction. Also because it is a function of z . As going deeper, the baroclinic force is bigger.

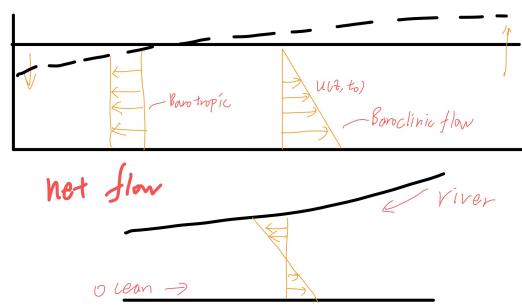


Figure 1: Costal Estuary

1.5 Rotating effects

the momentum eq

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x_i} + \nu \nabla^2 u_i + g_i \quad (1.27)$$

is hold in the fixed reference frame. Consider a reference frame rotating at Ω . We define \mathbf{r} to be the pos vector from $(x_1, x_2, x_3) = (0, 0, 0)$, \mathbf{u}, \mathbf{a} is velocity and acceleration vectors. Use subscript F as fixed frame and R as rotating frame. so $\frac{\partial \mathbf{u}_F}{\partial t}|_F = \mathbf{a}_F$ is the time rate of change, observed in a fixed frame, of the velocity observed in fixed frame. Also works for $\frac{\partial \mathbf{u}_R}{\partial t}|_R = \mathbf{a}_R$.

For any vector \mathbf{p} , there is

$$\left(\frac{d\mathbf{p}}{dt} \right)_F = \left(\frac{d\mathbf{p}}{dt} \right)_R + \Omega \times \mathbf{p} \quad (1.28)$$

So using \mathbf{r} , we get

$$\left(\frac{d\mathbf{r}}{dt} \right)_F = \left(\frac{d\mathbf{r}}{dt} \right)_R + \Omega \times \mathbf{r} \quad \mathbf{u}_F = \mathbf{u}_R + \Omega \times \mathbf{r} \quad (1.29)$$

again,

$$\left(\frac{d\mathbf{u}_F}{dt} \right)_F = \left(\frac{d}{dt} (\mathbf{u}_R + \Omega \times \mathbf{r}) \right)_F \quad (1.30)$$

$$= \left(\frac{d}{dt} (\mathbf{u}_R + \Omega \times \mathbf{r}) \right)_R + \Omega \times (\mathbf{u}_R + (\Omega \times \mathbf{r})) \quad (1.31)$$

$$= \left(\frac{d\mathbf{u}_R}{dt} \right)_R + \left(\frac{d}{dt} (\Omega \times \mathbf{r}) \right)_R + \Omega \times \mathbf{u}_R + \Omega \times (\Omega \times \mathbf{r}) \quad (1.32)$$

as $\frac{d}{dt}(\Omega \times \mathbf{r})_R = \Omega \times \mathbf{u}_R$, $\Omega \times \Omega \times \mathbf{r} = -\Omega^2 \mathbf{r}$,

Question 2:

$$\Omega \times (\Omega \times \mathbf{r}) = \Omega(\Omega \cdot \mathbf{r}) - \Omega^2 \mathbf{r} \text{ ans: TBD}$$

$$\left(\frac{d\mathbf{u}_F}{dt} \right)_F = \left(\frac{d\mathbf{u}_R}{dt} \right)_R + 2(\Omega \times \mathbf{u}_R) - \Omega^2 \mathbf{r} \quad (1.33)$$

so we have 2 new terms.

$$\frac{d\mathbf{u}}{dt} = -\frac{1}{\rho_0} \nabla p + \nu \nabla^2 \mathbf{u} + (\mathbf{g} + \boldsymbol{\Omega}^2 \mathbf{r}) - 2(\boldsymbol{\Omega} \times \mathbf{u}) \quad (1.34)$$

$\boldsymbol{\Omega}^2 \mathbf{r}$ is centrifugal acceleration which is often neglected because it is small compared to \mathbf{g} . The last term is coriolis force.

Example 1.1: 2D Coriolis Force

For example, $x_1 - x_2$ plane, rotation vector along x_3 . we will get

$$\frac{\partial u_1}{\partial t} + \dots = \dots + fu_2 \quad \frac{\partial u_2}{\partial t} + \dots = \dots - fu_1 \quad (1.35)$$

where $f = 2|\boldsymbol{\Omega}|$. At $t = 0$, $\mathbf{u} = (u_0, 0)$, the object will go around a circle.

$$\frac{\partial u_1}{\partial t} + u_1 \frac{\partial u_1}{\partial x_1} + u_2 \frac{\partial u_1}{\partial x_2} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x_1} + \nu \nabla^2 u_1 + fu_2 \quad (1.36)$$

comparing the advection term and coriolis term,

$$u_1 \frac{\partial u_1}{\partial x_1} \approx \frac{U^2}{L} \quad fu_2 \approx fU \quad \Rightarrow \quad Ro = \frac{U}{fL} \quad (1.37)$$

We get Rossby number.

Question 3:

We assume u_1 and u_2 have same magnitude U when deriving Ro . What if, like in horizontal flow, $u_1 \ll u_2$? Is Ro still make sense?

ans: when rotating make sense, we are considering 2D problem, and u_1 and u_2 will have same magnitude.

Question 4:

Is there a unitless number measuring the strength of stratification? ans: Ri

1.6 vorticity equation

local rotational (angular) velocity of a fluid element. $\boldsymbol{\omega}$ can complete description of flow field. $\boldsymbol{\omega} = \nabla \times \mathbf{u}$. Taking curl to NS equ, constant ρ case.

$$\nabla \times \left[\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right] = -\frac{1}{\rho_0} \nabla p + \mathbf{g} + \nu \nabla^2 \mathbf{u} \quad (1.38)$$

Consider each term,

$$\nabla \times \frac{\partial \mathbf{u}}{\partial t} = \frac{\partial}{\partial t} (\nabla \times \mathbf{u}) = \frac{\partial \boldsymbol{\omega}}{\partial t} \quad (1.39)$$

$$\nabla \times (\nu \nabla^2 \mathbf{u}) = \nu \nabla^2 \boldsymbol{\omega} \quad (1.40)$$

$$\nabla \times \nabla p = \mathbf{0} \quad \nabla \times \mathbf{g} = \mathbf{0} \quad (1.41)$$

For advection term,

$$\nabla \times (\mathbf{u} \cdot \nabla \mathbf{u}) = \nabla \times (\boldsymbol{\omega} \times \mathbf{u}) + \frac{1}{2} \nabla \times (\nabla(\mathbf{u} \cdot \mathbf{u})) \quad (1.42)$$

$$\nabla \times (\boldsymbol{\omega} \times \mathbf{u}) = \mathbf{u} \cdot \nabla \boldsymbol{\omega} - \boldsymbol{\omega} \cdot \nabla \mathbf{u} \quad (1.43)$$

We finally get

$$\frac{D\boldsymbol{\omega}}{Dt} = \frac{\partial \boldsymbol{\omega}}{\partial t} + \mathbf{u} \cdot \nabla \boldsymbol{\omega} = \boldsymbol{\omega} \cdot \nabla \mathbf{u} + \nu \nabla^2 \boldsymbol{\omega} \quad (1.44)$$

So there is a new term $\boldsymbol{\omega} \cdot \nabla \mathbf{u}$. e.g.

$$\frac{\partial \omega_1}{\partial t} = \omega_1 \frac{\partial u_1}{\partial x_1} + \omega_2 \frac{\partial u_1}{\partial x_2} + \omega_3 \frac{\partial u_1}{\partial x_3} \quad (1.45)$$

note $\frac{\partial u_1}{\partial x_1}$ measures the stretch of fluid, so if fluid is stretched long, the vorticity will increase.

Example 1.2: Vorticity from Straining

Take ω_1 as example.

$$\frac{\partial \omega_1}{\partial t} + u_j \frac{\partial \omega_1}{\partial x_j} = \nu \nabla^2 \omega_1 + \omega_j \frac{\partial u_1}{\partial x_j} \quad (1.46)$$

the first three terms are advection-diffusion of ω_1 , the last term is stretching and straining of $\boldsymbol{\omega}$.

$$\frac{\partial \omega_1}{\partial t} \dots = \dots + \omega_1 \frac{\partial u_1}{\partial x_1} + \omega_2 \frac{\partial u_1}{\partial x_2} + \omega_3 \frac{\partial u_1}{\partial x_3} \quad (1.47)$$

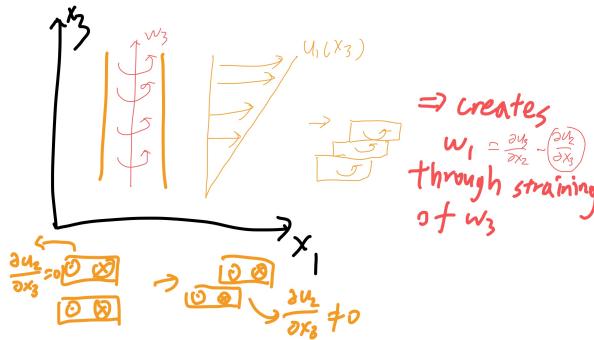


Figure 2: vorticity from straining

1.7 Variable density

$$\frac{\partial \mathbf{u}}{\partial t} \dots = -\frac{1}{\rho} \nabla p + \dots \quad (1.48)$$

taking curl, the new term is

$$\nabla \times \left(-\frac{1}{\rho} \nabla p \right) \rightarrow \epsilon_{ijk} \frac{\partial}{\partial x_j} \left(-\frac{1}{\rho} \nabla p \right) \quad (1.49)$$

$$= \epsilon_{ijk} \left(-\frac{1}{\rho} \right) \frac{\partial^2 p}{\partial x_j \partial x_k} + \epsilon_{ijk} \left(\frac{1}{\rho^2} \frac{\partial \rho}{\partial x_j} \right) \frac{\partial p}{\partial x_k} \quad (1.50)$$

$$= \frac{1}{\rho} \left[\epsilon_{ijk} \frac{\partial \rho}{\partial x_j} \frac{\partial p}{\partial x_k} \right] \quad (1.51)$$

$$= \frac{1}{\rho^2} \nabla \rho \times \nabla p \quad (1.52)$$

now the equation is

$$\frac{\partial \boldsymbol{\omega}}{\partial t} + \mathbf{u} \cdot \nabla \boldsymbol{\omega} = \nu \nabla^2 \boldsymbol{\omega} + \boldsymbol{\omega} \cdot \nabla \mathbf{u} + \frac{1}{\rho^2} \nabla \rho \times \nabla p \quad (1.53)$$

the last new term is a source term. If $\nabla \rho$ aligns with ∇p then it is zero. If not, there will be baroclinic vorticity production. Just like the Long Box problem.

Important:

Without the new term, initial $\boldsymbol{\omega} = \mathbf{0}$ will lead to $\boldsymbol{\omega} = \mathbf{0}$ all times. But with this term, even initial $\boldsymbol{\omega} = \mathbf{0}$, there will be vorticity generation.

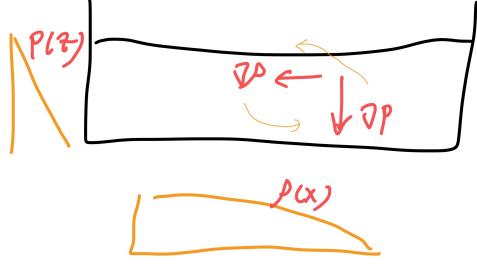


Figure 3: Baroclinic Long Box

1.8 Fluid Column Model

set up grid from $z = 0$ to $z = H$, z_1, z_2, \dots, z_N . Concentration $C(z, t)$, velocity $u(z, t)$, temperature $T(z, t)$, Salinity $S(z, t)$, pressure $p(z, t)$. We focus on concentration first. The equation is

$$\frac{\partial C}{\partial t} = \frac{\partial}{\partial z} \left(D \frac{\partial C}{\partial z} \right) \quad (1.54)$$

lhs use Implicit/Explicit time advancement. Using implicit method,

$$\frac{1}{\Delta t} (C_i^{n+1} - C_i^n) = \left[\frac{\partial}{\partial z} \left(D \frac{\partial C}{\partial z} \right) \right]^{n+1} = \frac{1}{\Delta z} \left(\left(D \frac{\partial C}{\partial z} \right)_{i+1/2} - \left(D \frac{\partial C}{\partial z} \right)_{i-1/2} \right) \quad (1.55)$$

(also show explicit here:)

$$\frac{D\Delta t}{\Delta z^2} < \beta \Rightarrow \Delta t < \beta \frac{\Delta z^2}{D} \quad (1.56)$$

also

$$\left(D \frac{\partial C}{\partial z} \right)_{i+1/2} = D_{i+1/2} \frac{1}{\Delta z} (C_{i+1}^{n+1} - C_i^{n+1}) \quad \left(D \frac{\partial C}{\partial z} \right)_{i-1/2} = D_{i-1/2} \frac{1}{\Delta z} (C_i^{n+1} - C_{i-1}^{n+1}) \quad (1.57)$$

finally

$$\frac{1}{\Delta t} (C_i^{n+1} - C_i^n) = \frac{1}{\Delta z^2} [D_{i+1/2} C_{i+1}^{n+1} - (D_{i+1/2} + D_{i-1/2}) C_i^{n+1} + D_{i-1/2} C_{i-1}^{n+1}] \quad (1.58)$$

so the full equation can be written

$$\left[-\frac{\Delta t}{\Delta z^2} D_{i+1/2} \right] C_{i+1}^{n+1} + \left[1 + \frac{\Delta t}{\Delta z^2} (D_{i+1/2} + D_{i-1/2}) \right] C_i^{n+1} + \left[-\frac{\Delta t}{\Delta z^2} D_{i-1/2} \right] C_{i-1}^{n+1} = C_i^n \quad (1.59)$$

this can be expressed in matrix form. In matlab just use.

$$C^{n+1} = \text{tridiag}(a, b, c, C^n) \quad (1.60)$$

For B.C., most common we will use Neumann BC to specify gradient of a quantity at $z = 0$ or H . If $\frac{\partial C}{\partial z} = 0$ at $z = 0, H$, or specified C' . At $i = 1$, $z = \Delta z$, assume D constant,

$$C_1^{n+1} = C_1^n + \frac{\Delta t D}{\Delta z^2} [C_2^{n+1} - 2C_1^{n+1} + C_0^{n+1}] \quad (1.61)$$

we use

$$\frac{\partial C}{\partial z} \sim \frac{C_1 - C_0}{\Delta z} = C' \Rightarrow C_0 = C_1 - \Delta z C' \quad (1.62)$$

so the C_1^{n+1} changes into

$$C_1^{n+1} = C_1^n + \frac{\Delta t D}{\Delta z^2} [C_2^{n+1} - 2C_1^{n+1} + C_1^{n+1} - \Delta z C'] \quad (1.63)$$

$$= C_1^n + \frac{\Delta t D}{\Delta z^2} [C_2^{n+1} - C_1^{n+1}] - \frac{\Delta t D}{\Delta z} C' \quad (1.64)$$

$$\left[-\frac{\Delta t D}{\Delta z^2} \right] C_2^{n+1} + \left[1 + \frac{\Delta t D}{\Delta z^2} \right] C_1^{n+1} = C_1^n - \frac{\Delta t D}{\Delta z} C' \quad (1.65)$$

2 Turbulent Flows

2.1 What is turbulent flow

Turbulent flow is characterized by 3 features:

1. 3d flow structures
2. unsteady
3. contain a wide range of “scales”, spatial and temporal variability

A laminar flow is stable with time, but turbulent flow varies around initial speed a lot. Define mean/average velocity profile $\bar{u}(z)$, then we can use deviation $u'(z, t)$ (called turbulent/fluctuation velocity) to analyze.

2.2 Averaging in turbulent flow

Consider evolving mean flow.

- The easiest way to visualize is to use time average

$$(u)(z, t) = \frac{1}{T} \int_{-T/2}^{T/2} u(z, t) dt \quad (2.1)$$

But T can be differently chosen. In order to be effective, it requires T to be longer than turbulent variations, but is shorter than mean flow variations.

Think of hydrograph in river, its mean flow time scale may be days, but turbulent time scale may only be seconds. Then think of flow under waves, the mean flow time scale is only seconds, so we cannot take time averages.

Hydrograph is the flux-time plot $Q(t)$

- The second method is ensemble average. That is creating a set of N realizations, i th is $u(z, t)$, then

$$\bar{u}(z, t) = \frac{1}{N} \sum_{i=1}^N u_i(z, t) \quad (2.2)$$

- The third method is raynolds average. It is simply a separation of velocity into mean \bar{u} and turbulent u' components.

Consider the scale of u', v', w' first.

Turbulent eddy: streamline shows overturning motion. Eddies are useful in describing turbulent length scales. The size of turbulent eddy is denoted as λ_t where t refers to turbulence. It also has velocity scale u_t . The time scale, is $\tau_t = \lambda_t/u_t$

How to estimate u_t, λ_t, τ_t ? Use root-mean-square of $u'(t)$ to calculate u_t . Integral time scale τ_t . Mean of turbulent velocities equals 0. That is

$$\bar{u}' = \bar{v}' = \bar{w}' = 0 \quad (2.3)$$

the overline means Raynolds average. However,

$$\overline{(u')^2}, \overline{(v')^2}, \overline{(w')^2} \neq 0 \quad (2.4)$$

Let Turbulent Kinetic Energy, or TKE, which is the key factor, to be

$$q^2 = \overline{(u')^2} + \overline{(v')^2} + \overline{(w')^2} \quad \text{or} \quad k = \frac{1}{2} \left(\overline{(u')^2} + \overline{(v')^2} + \overline{(w')^2} \right) \quad (2.5)$$

2.3 Turbulent Scale and Properties

Turbulent Scales

Turbulent length scales goes from largest: constrained by solid boundaries; smallest: constrained by viscosity.

Large scales Set by boundaries and motions are set by external forcing. Get energy from outside.

Intermediate Get energy from Large scale, transfer to smaller scale.

Small scales Set by viscosity. Energy dissipated by viscosity.

If we say turbulent is **steady**, we mean the energy flows through this system is stable, assign ϵ to it as the Turbulent Dissipation Rate. As energy is conserved, the rate of energy transfer in all process will also be ϵ . This is known as Energy Cascade.

Smallest scales respond only to ϵ and ν , they don't care about the larger scale process. So the energy conservation simply leads to the Kolmogorov Length Scale $\lambda_\nu = (\nu^3/\epsilon)^{1/4}$. This scale is the smallest

Kolmogorov Spectrum for turbulent. For spectrum we use wavenumber $k = \lambda^{-1}$ where λ is the length scale. Energy density $E(k)$ is the energy per wavenumber.

$$q^2 = \int_0^\infty E(k) dk \quad (2.6)$$

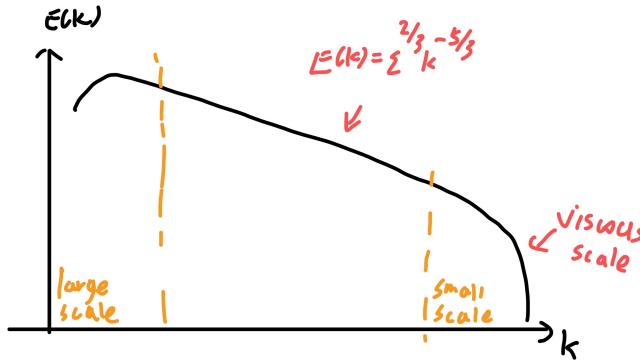


Figure 4: Turbulence energy spectrum (Steady)

The large scale has most energy and is dominant in affecting density mixing and other effects.

For the largest turbulent scale, we use u_t, λ_t, τ_t to refer to velocity, length and time scale. e.g., the velocity scale can be rms of \bar{u}' , $\sqrt{q^2}$, length scale can be H , $u_t \tau_t$, time scale can be q^2/ϵ .

The correlation, or Integral time scale, can be calculated from lagged auto-correlation.

$$R(\Delta t) = \overline{u'(t) \cdot u'(t + \Delta t)} / \overline{(u')^2} \quad (2.7)$$

In real turbulent flow, $R(\Delta t)$ usually starts from 1 at $\Delta t = 0$ then drops as Δt increases. Integrate it to get the Integral time scale:

$$\tau_t = \int_0^\infty R(\Delta t) d(\Delta t) \quad (2.8)$$

The time scale here represent how long the flow is similar to itself, or say how long the turbulence will change.

2.4 Turbulent Diffusion Equation

Start with advection-diffusion equation

$$\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} + w \frac{\partial C}{\partial z} = D \nabla^2 C \quad (2.9)$$

With turbulent flow, $C = \bar{C} + C'$, $u = \bar{u} + u'$, $v = \bar{v} + v'$, $w = \bar{w} + w'$. We mainly want to know $\bar{C}(x, y, z, t)$. Using continuity equation,

$$\frac{\partial C}{\partial t} + \frac{\partial}{\partial x}(uC) + \frac{\partial}{\partial y}(vC) + \frac{\partial}{\partial z}(wC) = D\nabla^2 C \quad (2.10)$$

Now apply average in each term, we get

$$\frac{\partial \bar{C}}{\partial t} + \frac{\partial}{\partial x}(\bar{u}\bar{C}) + \frac{\partial}{\partial y}(\bar{v}\bar{C}) + \frac{\partial}{\partial z}(\bar{w}\bar{C}) = D\nabla^2 \bar{C} \quad (2.11)$$

Substituting,

$$\begin{aligned} \frac{\partial(\bar{C} + C')}{\partial t} + \frac{\partial}{\partial x}((\bar{u} + u')(\bar{C} + C')) + \frac{\partial}{\partial y}((\bar{v} + v')(\bar{C} + C')) + \frac{\partial}{\partial z}((\bar{w} + w')(\bar{C} + C')) \\ = D\nabla^2(\bar{C} + C') \end{aligned} \quad (2.12)$$

with some properties,

$$\bar{f} + g = \bar{f} + \bar{g} \quad \bar{f} + f' = \bar{\bar{f}} + \bar{f}' = \bar{f} \quad \bar{f}'g' \neq 0 \quad \bar{\bar{f}}\bar{g} = \bar{f}\bar{g} \quad (2.13)$$

$$(\bar{u} + u')(\bar{C} + C') = \bar{u}\bar{C} + \underbrace{\bar{u}C'}_{=0} + \underbrace{u'\bar{C}}_{=0} + u'C' = \bar{u}\bar{C} + u'C' \quad (2.14)$$

The correlation term $\bar{u}'C'$ is a new term. Putting back,

$$\frac{\partial \bar{C}}{\partial t} + \bar{u}\frac{\partial \bar{C}}{\partial x} + \bar{v}\frac{\partial \bar{C}}{\partial y} + \bar{w}\frac{\partial \bar{C}}{\partial z} = D\nabla^2 \bar{C} - \frac{\partial}{\partial x}(\bar{u}'C') - \frac{\partial}{\partial y}(\bar{v}'C') - \frac{\partial}{\partial z}(\bar{w}'C') \quad (2.15)$$

Those new terms on the *rhs* represents the turbulent mixing. Take $\bar{w}'C'$ term for example,

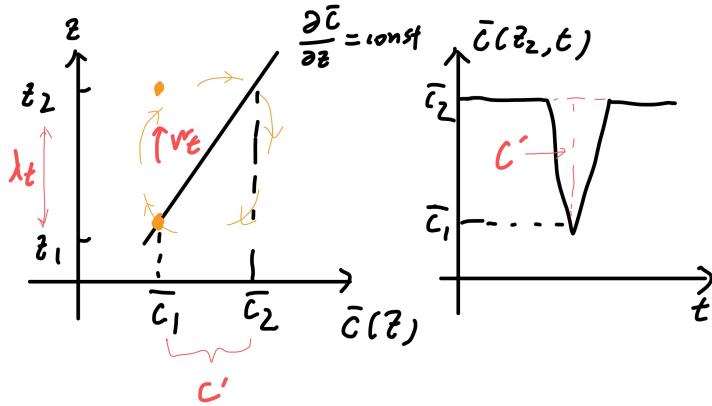


Figure 5: Turbulence diffusion example. The Yellow circle represents the turbulence. A parcel was carried by turbulence from z_1 to z_2 , causing the concentration at z_2 to drop at certain time.

We approximately calculate the term as

$$\bar{w}'C' \approx -w_t \lambda_t \frac{\partial \bar{C}}{\partial z} \quad (2.16)$$

and define $k_t = w_t \lambda_t$ is Turbulent Diffusion Coefficient

$$\frac{\partial \bar{C}}{\partial t} + \dots = D \nabla^2 \bar{C} + \dots - \frac{\partial}{\partial z} \left(-w_t \lambda_t \frac{\partial \bar{C}}{\partial z} \right) = D \nabla^2 \bar{C} + \dots + \frac{\partial}{\partial z} \left(k_t \frac{\partial \bar{C}}{\partial z} \right) \quad (2.17)$$

if $u_t \approx v_t \approx w_t$, which is called isotropic turbulence, then it is same for x and y dir.

$$\frac{\partial \bar{C}}{\partial t} + \bar{u} \frac{\partial \bar{C}}{\partial x} + \bar{v} \frac{\partial \bar{C}}{\partial y} + \bar{w} \frac{\partial \bar{C}}{\partial z} = D \nabla^2 \bar{C} + \frac{\partial}{\partial x} \left(k_t \frac{\partial \bar{C}}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_t \frac{\partial \bar{C}}{\partial y} \right) + \frac{\partial}{\partial z} \left(k_t \frac{\partial \bar{C}}{\partial z} \right) \quad (2.18)$$

if k_t is not a function of x, y, z , the *rhs* becomes $(D + k_t) \nabla^2 \bar{C}$. Usually $D \ll k_t$.

Turbulent Properties Comparison

1. Homogeneous turbulence, means $\bar{(u')}, \bar{(v')}, \bar{(w')}$ is not a function of x, y, z .
2. Isotropic turbulence: $\bar{(u')^2} \approx \bar{(v')^2} \approx \bar{(w')^2}$. If there is boundary, external force, or stratification, this assumption may not holds.
3. Steady turbulence: $\bar{(u')^2}, \bar{(v')^2}, \bar{(w')^2}$ is not a function of t .

It is same for NS equation.

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \nu \nabla^2 u_i \quad (2.19)$$

changes into

$$\frac{\partial \bar{u}_i}{\partial t} + \bar{u}_j \frac{\partial \bar{u}_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \nabla^2 \bar{u}_i - \frac{\partial}{\partial x_j} (\bar{u}_i' \bar{u}_j') \quad (2.20)$$

the last new term is called turbulent stresses. It act like viscous stresses, but based on turbulent motions. $\bar{u}' \bar{u}'$ is vertical transport of horizontal momentum. We can define $\nu_t = u_t \lambda_t$, which is turbulent viscosity.

$$\frac{\partial \bar{u}_i}{\partial t} + \bar{u}_j \frac{\partial \bar{u}_i}{\partial x_j} = -\frac{1}{\rho_0} \frac{\partial \bar{p}}{\partial x_i} + \nu \nabla^2 \bar{u}_i + g_i + \frac{\partial}{\partial x_j} \left(\nu_t \frac{\partial \bar{u}_i}{\partial x_j} \right) \quad (2.21)$$

Where estimating ν_t is the core for turbulence modeling.

2.5 Turbulent Models

Consider a case, flat bottom, general depth H , slight slope top surface $\frac{\partial \eta}{\partial x} = \text{const}$. Steady flow $\bar{v} = \bar{w} = 0$, \bar{u} is not a function of x , but a function of z .

$$0 = -\frac{1}{\rho_0} \frac{\partial \bar{p}}{\partial x} + \nu \frac{\partial^2 \bar{u}}{\partial z^2} - \frac{\partial}{\partial z} (\bar{u}' \bar{w}') - \underbrace{\frac{\partial}{\partial y} (\bar{u}' \bar{v}') - \frac{\partial}{\partial x} (\bar{u}' \bar{u}')}_{=0} \quad (2.22)$$

molecular viscous stress \ll turbulent, so neglect.

$$-\frac{1}{\rho_0} \frac{\partial \bar{p}}{\partial x} = \frac{\partial}{\partial z} (\bar{u}' \bar{w}') \quad (2.23)$$

Depth average from $0 \rightarrow H$,

$$\frac{1}{H} \int_0^H -\frac{1}{\rho_0} \frac{\partial \bar{p}}{\partial x} dz = \frac{1}{H} \int_0^H \frac{\partial}{\partial z} (\bar{u}' \bar{w}') dz \quad (2.24)$$

the *lhs*,

$$-\frac{1}{\rho_0} \frac{\partial \bar{p}}{\partial x} = -g \frac{\partial \eta}{\partial x} \quad (2.25)$$

so

$$-g \frac{\partial \eta}{\partial x} = \frac{1}{H} [\bar{u}' \bar{w}'(H) - \bar{u}' \bar{w}'(0)] \quad (2.26)$$

assume free surface, so no free slip. Then $\tau = 0$, so $\bar{u}' \bar{w}'(H) = 0$. then

$$\underbrace{\rho_0 g H \frac{\partial \eta}{\partial x}}_{\tau_{bed}} = \rho_0 \bar{u}' \bar{w}'(z=0) \quad (2.27)$$

The turbulence actually is transporting horizontal momentum vertically to the bed, so $\rho_0 \bar{u}' \bar{w}'$ can be written as $\bar{w}'(\rho_0 \bar{u}')$. Near the boundary, the turbulent motions are limited. $\frac{\partial \bar{u}}{\partial z}$ increase.

Previously we know

$$-\bar{u}' \bar{w}' = \nu_t \frac{\partial \bar{u}}{\partial z} \quad -\bar{w}' \bar{C}' = k_t \frac{\partial \bar{C}}{\partial z} \quad (2.28)$$

But actually the coefficient should be defined as

$$\nu_t = \frac{-\bar{u}' \bar{w}'}{\frac{\partial \bar{u}}{\partial z}} \quad k_t = \frac{-\bar{w}' \bar{C}'}{\frac{\partial \bar{C}}{\partial z}} \quad (2.29)$$

So how to define ν_t, k_t ? Actually there are ν_x, ν_y, ν_z . But if we make isotropic turbulence assumption, then $\nu_t = \nu_x = \nu_y = \nu_z$. Same for k_t . And we assume $\nu_t = \beta k_t$, β is an order 1 number. .

Modeling for ν_t . $\nu_t = k_t = u_t \lambda_t$. Mixing (scalar or momentum) is dominated by the largest turbulent scales. So λ_t is largest scales, u_t is energy-containig scales.

Some models:

0-equation model scalinquestionates: mean flow or external forcing. λ_t is set by physical boundaries. u_t is bulk forcing, channal flow.

$$\tau_b = \rho \bar{u}' \bar{w}'(z=0) = \rho g H \frac{\partial \eta}{\partial x} \quad (2.30)$$

and $\tau_b = \rho u_*^2$, u_* is friction velocity. So $\bar{u}' \bar{w}'(z=0) = u_*^2$ leads to approximation $u_t \approx u_*$.

$$\tau_b = \rho u_x^2 = \rho C_D \bar{u}^2 \Rightarrow u_* = \sqrt{C_D} \bar{u} \approx u_t \quad (2.31)$$

C_D is Empirical drag coefficient, depends on the height at which \bar{u} is evaluated. It depends on roughness of surface. $C_D \approx 0.0025$ for muddy, $u_* \approx 0.05 \bar{u}$

Estimating λ_t , as turbulence can not go into boundary, then $\lambda_t \leq 2z$. For Vonkarman's constant, $k = 0.41$.

$$\lambda_t = kz \quad (z < H/2) \quad \lambda_t = k(H - z) \quad (z > H/2) \quad (2.32)$$

or more smoothly,

$$\lambda_t = kH \frac{z}{H} \left(1 - \frac{z}{H}\right) \quad \lambda_t^{max} = \frac{1}{4} kH \quad \lambda_t^{avg} = \frac{1}{6} kH \quad (2.33)$$

In summary.

$$u_t = u_* \quad \lambda_t = f(kH) \quad (2.34)$$

But what we are missing, is loss of structure/variability of turbulent energetics and influence of stratification.

This assumption breaks down for sediment

1-equation model similar, $\lambda_t = f(kH)$, but for $u_t = \sqrt{q^2}$. q^2 is solved from

$$\frac{\partial q^2}{\partial t} + \overline{u_j} \frac{\partial q^2}{\partial x_j} = \dots \quad (2.35)$$

2-equation model still $u_t = \sqrt{q^2}$, but λ_t is calc from second turbulence variable. e.g., $\epsilon(x, y, z, t)$, $\lambda_t = (q^2)^{3/2}/\epsilon$. Also known as $k - \epsilon$ models. For Mellor-Yamada models. use $q^2 \lambda_t$, as with same unit,

$$\int_0^\infty \overline{u'(x)u'(x+\delta)} d\delta \Rightarrow q^2 L \quad (2.36)$$

A note on the code: models

$$\frac{\partial u}{\partial t} = \underbrace{-\frac{1}{\rho_0} \frac{\partial p}{\partial x}}_{f(t)} + \underbrace{\frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right)}_{\text{implicit}} \quad (2.37)$$

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \left(-\frac{1}{\rho} \frac{\partial p}{\partial x} \right)^{n+1} + \left(\frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) \right)_i^{n+1} \quad (2.38)$$

$$u_i^{n+1} - \left(\frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) \right)_i^{n+1} = \Delta t \overline{-\frac{1}{\rho_0} \frac{\partial p}{\partial x}} + u_i^n \quad (2.39)$$

where $u_i^n \rightarrow u_p(z)$

Turbulence models

0-eqn Physical scaling: $\lambda_t \approx H$, $u_t \approx u_*$

1-eqn $\lambda_t \approx H$, $u_t = q$

2-eqn $u_t = q$, $\epsilon(x, y, z, t)$, $q^2 l(x, y, z, t)$

2.6 Turbulent Energy Equation

We want an equation for $q^2(x, y, z, t)$. Boundary layer approximation, horizontal scales of problem \ll vertical, which means vertical gradients \gg horizontal gradients. Assume $\frac{\partial}{\partial x} = 0$, then $\frac{\partial}{\partial y} \rightarrow 0$. With continuity, we know $\frac{\partial w}{\partial z} = 0$, further apply to $w = 0$ boundary, we get $w = 0$.

Focus on x component $\overline{u'}$. For full velocity,

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(uu) + \frac{\partial}{\partial y}(uv) + \frac{\partial}{\partial z}(uw) = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \nu \nabla^2 u \quad (2.40)$$

and $u = \overline{u} + u'$, $v = \overline{v} + v'$, $w = \overline{w} + w'$, $p = \overline{p} + p'$, get RANS

$$\frac{\partial \overline{u}}{\partial t} + \frac{\partial}{\partial x}(\overline{uu}) + \frac{\partial}{\partial y}(\overline{uv}) + \frac{\partial}{\partial z}(\overline{uw}) = -\frac{1}{\rho_0} \frac{\partial \overline{p}}{\partial x} + \nu \nabla^2 \overline{u} - \frac{\partial}{\partial x}(\overline{u'u'}) - \frac{\partial}{\partial y}(\overline{u'v'}) - \frac{\partial}{\partial z}(\overline{u'w'}) \quad (2.41)$$

let Equation 2.40 minus Equation 2.41, we get

$$\begin{aligned} \frac{\partial u'}{\partial t} + \frac{\partial}{\partial x}(2\overline{u}u' + u'u') + \frac{\partial}{\partial y}(\overline{uv}' + u'\overline{v} + u'v') + \frac{\partial}{\partial z}(\overline{uw}' + u'\overline{w} + u'w') \\ = -\frac{1}{\rho_0} \frac{\partial p'}{\partial x} + \nu \nabla^2 u' + \frac{\partial}{\partial x}(\overline{u'u'}) + \frac{\partial}{\partial y}(\overline{u'v'}) + \frac{\partial}{\partial z}(\overline{u'w'}) \end{aligned} \quad (2.42)$$

we want a equation for $\overline{u'^2}$, and

$$u' \frac{\partial u'}{\partial t} = \frac{\partial}{\partial t} \left(\frac{1}{2} u'^2 \right) \quad (2.43)$$

so multiply each term with u' , then take Raynold average, obviously $\overline{u' \frac{\partial}{\partial x} (\overline{u' u'})}$ term vanished.

$$\begin{aligned} \frac{\partial}{\partial t} \left(\frac{1}{2} \overline{u'^2} \right) &+ \overline{2u' \frac{\partial}{\partial x} (\overline{u' u'})} + \overline{u' \frac{\partial}{\partial x} (u' u')} \\ &+ \overline{u' \frac{\partial}{\partial y} (\overline{u' v'})} + \underbrace{\overline{u' \frac{\partial}{\partial y} (u' \overline{v})} + \overline{u' \frac{\partial}{\partial y} (u' v')}}_{\text{term 5}} \\ &+ \overline{u' \frac{\partial}{\partial z} (\overline{u' w'})} + \overline{u' \frac{\partial}{\partial z} (u' \overline{w})} + \underbrace{\overline{u' \frac{\partial}{\partial z} (u' w')}}_{\text{term 9}} \\ &= -u' \frac{1}{\rho_0} \frac{\partial p'}{\partial x} + \underbrace{\nu u' \nabla^2 u'}_{\text{term 11}} \quad (2.44) \end{aligned}$$

For term 9,

$$\overline{u' \frac{\partial}{\partial z} (u' w')} = \frac{1}{2} \frac{\partial}{\partial z} \overline{w' u'^2} = \frac{\partial}{\partial z} \left(\overline{w' \frac{1}{2} u'^2} \right) \quad (2.45)$$

this term looks like $\overline{w' C'}$, where $C' = u'^2/2$, so we can use similar model

$$\overline{w' C'} = k_t \frac{\partial \overline{C}}{\partial z} \Rightarrow \frac{\partial}{\partial z} \left(\overline{w' (u'^2/2)} \right) = \frac{\partial}{\partial z} \left(k_q \frac{\partial}{\partial z} (\overline{u'^2}/2) \right) \quad (2.46)$$

where k_q is turbulent diffusion coefficient for turbulent energy. Term 3,6,9 are turbulent diffusion of TKE. Other $u' u'$, $u' v'$ term can be similarly treated too. For term 11, simply let $\nu u' \nabla^2 u' = \epsilon$. For term 5,

$$\overline{u' \frac{\partial}{\partial y} (u' \overline{v})} = \overline{u' u' \frac{\partial \overline{v}}{\partial y}} + \overline{u' \overline{v} \frac{\partial u'}{\partial y}} = \underbrace{\overline{u' u' \frac{\partial \overline{v}}{\partial y}}}_{\text{term 5a}} + \underbrace{\overline{v} \frac{\partial}{\partial y} (\overline{u'^2}/2)}_{\text{Advection of TKE by mean flow}} \quad (2.47)$$

For term 8, it is similar.

$$\overline{u' \frac{\partial}{\partial z} (u' \overline{w})} = \underbrace{\overline{u' u' \frac{\partial \overline{w}}{\partial z}}}_{\text{term 8a}} + \overline{w} \frac{\partial}{\partial z} (\overline{u'^2}/2) \quad (2.48)$$

For term 4,

$$\overline{u' \frac{\partial}{\partial y} (\overline{u' v'})} = \overline{\overline{u} u' \frac{\partial v'}{\partial y}} + \overline{u' v'} \frac{\partial \overline{u}}{\partial y} \quad (2.49)$$

For term 7,

$$\overline{u' \frac{\partial}{\partial z} (\overline{u' w'})} = \overline{\overline{u} u' \frac{\partial w'}{\partial y}} + \overline{u' w'} \frac{\partial \overline{u}}{\partial z} \quad (2.50)$$

For term 2,

$$2 \overline{u' \frac{\partial}{\partial x} (\overline{u' u'})} = 2 \overline{\overline{u} u' \frac{\partial u'}{\partial x}} + 2 \overline{u' u' \frac{\partial \overline{u}}{\partial x}} = \underbrace{\overline{\overline{u} u' \frac{\partial u'}{\partial x}}}_{\text{term 2a}} + \overline{\overline{u} \frac{\partial}{\partial x} (\overline{u'^2}/2)} + \underbrace{2 \overline{u' u' \frac{\partial \overline{u}}{\partial x}}}_{\text{term 2c}} \quad (2.51)$$

Add term 8a, 5a and 2c,

$$\overline{u'u'} \frac{\partial \bar{w}}{\partial z} + \overline{u'u'} \frac{\partial \bar{v}}{\partial y} + 2\overline{u'u'} \frac{\partial \bar{u}}{\partial x} = \overline{u'u'} \frac{\partial \bar{u}}{\partial x} \quad (2.52)$$

also works for 4a, 7a, 2a,

$$\overline{u'u'} \left(\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} + \frac{\partial w'}{\partial z} \right) = 0 \quad (2.53)$$

Finally,

$$\begin{aligned} & \underbrace{\frac{\partial}{\partial t} (\overline{u'^2}/2)}_{\text{unsteadiness}} + \underbrace{\bar{u} \frac{\partial}{\partial x} (\overline{u'^2}/2) + \bar{v} \frac{\partial}{\partial y} (\overline{u'^2}/2) + \bar{w} \frac{\partial}{\partial z} (\overline{u'^2}/2)}_{\text{advection}} \\ &= \underbrace{-u' \frac{1}{\rho_0} \frac{\partial p'}{\partial x} + \epsilon - \frac{\partial}{\partial x} (\overline{u'(u'^2/2)}) - \frac{\partial}{\partial y} (\overline{v'(u'^2/2)}) - \frac{\partial}{\partial z} (\overline{w'(u'^2/2)})}_{\text{Turbulent Diffusion}} \\ & \quad + \underbrace{\overline{u'u'} \frac{\partial \bar{u}}{\partial x} + \overline{u'v'} \frac{\partial \bar{u}}{\partial y} + \overline{u'w'} \frac{\partial \bar{u}}{\partial z}}_{P=\text{shear production}} \quad (2.54) \end{aligned}$$

The last one, shear production is a source term. Example,

$$\overline{u'w'} = -\nu_t \frac{\partial \bar{u}}{\partial z} \Rightarrow -\overline{u'w'} \frac{\partial \bar{u}}{\partial z} = -\nu_t \left(\frac{\partial \bar{u}}{\partial z} \right)^2 \geq 0 \quad (2.55)$$

As

$$\begin{aligned} \frac{\partial}{\partial t} (q^2/2) &= \bar{u} \frac{\partial}{\partial x} (q^2/2) + \bar{v} \frac{\partial}{\partial y} (q^2/2) + \bar{w} \frac{\partial}{\partial z} (q^2/2) \\ &= \frac{\partial}{\partial x} (k_q \frac{\partial}{\partial x} (q^2/2)) + \frac{\partial}{\partial y} (k_q \frac{\partial}{\partial y} (q^2/2)) + \frac{\partial}{\partial z} (k_q \frac{\partial}{\partial z} (q^2/2)) + P - \epsilon \quad (2.56) \end{aligned}$$

usually k_q are set to include the three terms below.

$$-u' \frac{1}{\rho_0} \frac{\partial p'}{\partial x} - v' \frac{1}{\rho_0} \frac{\partial p'}{\partial y} - w' \frac{1}{\rho_0} \frac{\partial p'}{\partial z} \quad (2.57)$$

$$\frac{\partial q^2}{\partial t} + u \frac{\partial q^2}{\partial x} + v \frac{\partial q^2}{\partial y} + w \frac{\partial q^2}{\partial z} = \frac{\partial}{\partial x} \left(k_q \frac{\partial q^2}{\partial x} \right) + \frac{\partial}{\partial y} \left(k_q \frac{\partial q^2}{\partial y} \right) + \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) + 2P - 2\epsilon \quad (2.58)$$

$$\frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) = \frac{\partial}{\partial z} \left[-\frac{1}{\rho_0} \overline{p'w'} - \overline{w'(u'^2 + v'^2 + w'^2)} \right] \quad (2.59)$$

$$\epsilon = -\nu \overline{u' \nabla^2 u'} - \nu \overline{v' \nabla^2 v'} - \nu \overline{w' \nabla^2 w'} \quad (2.60)$$

P contains 9 terms, interaction of mean slow and turbulence

$$P = - \underbrace{\overline{u'_i u'_j}}_{\text{turbulent stress}} \cdot \underbrace{\frac{\partial \bar{u}_i}{\partial x_j}}_{\text{mean shear}} \quad (2.61)$$

suppose $\bar{u}(z), \bar{v} = \bar{w} = 0$, general parallel shear flows. All the mean shear components are 0 except $\frac{\partial \bar{u}}{\partial z}$, which means shear production $P = -\overline{u'w'} \frac{\partial \bar{u}}{\partial z}$, but $\overline{u'w'} = -\nu_t \frac{\partial \bar{u}}{\partial z}$, so $P = \nu_t \left(\frac{\partial \bar{u}}{\partial z} \right)^2$.

2.7 Applications of TKE Equation

Example 2.1: Breaking waves on a motionless ocean

$\varepsilon \neq f(x, y, t)$, $q^2 \neq f(x, y, t) \rightarrow q^2(z)$, $\bar{u} = \bar{v} = \bar{w} = 0$, so $P = 0$, the equation is

$$0 = \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) - 2\epsilon \quad (2.62)$$

the q^2 is diffused deep into the ocean and dissipated.

Example 2.2: Internal Turbulent event

Stratified ocean, double profile $\rho_1 < \rho_2$. On the interface there is internal wave, it can reach a point where they overturn and break, causing patch of turbulence. $\bar{u}(z)$, $\bar{v} = \bar{w} = 0$, $q^2 = f(x, y, z, t)$,

$$\frac{\partial q^2}{\partial t} + \bar{u} \frac{\partial q^2}{\partial x} = \text{Diffusion Terms} + 2P - 2\epsilon \quad (2.63)$$

The advection term will create horizontal transport of q^2 .

Boundary layer Approximation, $\bar{u}(z, t)$, $\bar{v} = \bar{w} = 0$

$$\frac{\partial \bar{u}}{\partial t} = -\frac{1}{\rho_0} \frac{\partial \bar{p}}{\partial x} + \frac{\partial}{\partial z} \left(\nu_t \frac{\partial \bar{u}}{\partial z} \right) \quad (2.64)$$

where assume $\frac{\partial \bar{p}}{\partial x}$ is not a function of x .

$$\frac{\partial q^2}{\partial t} = \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) + \underbrace{2\nu_t \left(\frac{\partial \bar{u}}{\partial z} \right)^2}_{\text{source}} - 2\epsilon \quad (2.65)$$

The source term is large near boundary. Steady flow:

$$0 = \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) + 2P - 2\epsilon \quad \Rightarrow \quad \text{Diffusion} = 2\epsilon - 2P \quad (2.66)$$

diffusion depends on the balance of ϵ and P . But usually $\epsilon \approx P$, local equilibrium approximation $P = \epsilon$ is often hold for small shear case.

$$\frac{\partial \bar{u}}{\partial t} = -\frac{1}{\rho_0} \frac{\partial}{\partial z} \left(\nu_t \frac{\partial \bar{u}}{\partial z} \right) \quad (2.67)$$

$$\frac{\partial \bar{C}}{\partial t} = \frac{\partial}{\partial z} \left(k_t \frac{\partial \bar{C}}{\partial z} \right) \quad (2.68)$$

$$\frac{\partial q^2}{\partial t} = \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) + 2\nu_t \left(\frac{\partial \bar{u}}{\partial z} \right)^2 - 2\epsilon \quad (2.69)$$

$\nu_t \approx u_t \lambda_t \approx k_t \approx k_q$, $u_t = \sqrt{q^2}$, given λ_t , $\epsilon = (q^2)^{3/2}/\lambda_t$; given ϵ , $\lambda_t = (q^2)^{3/2}/\epsilon$. For λ_t , options are

1. $kz, kH, k\frac{z}{H}(1 - \frac{z}{H})$
2. Mellor-Yamada models, equation for $q^2 l$

3. $k - \epsilon$ models, $k = q^2/2$,

$$\frac{\partial \epsilon}{\partial t} = \frac{\partial}{\partial z} \left(k_q \frac{\partial \epsilon}{\partial z} \right) - \gamma_1 P \frac{\epsilon}{k} - \gamma_2 \frac{\epsilon^2}{k} \quad (2.70)$$

4. generalized lengthscale model. $\frac{\partial \lambda_t}{\partial t} + \dots$, can choose different coefficients to reproduce Mellor-Yamada and $k - \epsilon$ models.

In turbulent cascade, P input into large scale while ϵ output from large scale into intermediate scale. We are modeling large scale because it is dominate ν_t , k_t , q^2 as well as u_t, λ_t . Then we can ignore smaller scale, when the cascade is complete or fully developed turbulence.

Comparison of Forcing and Mixing timescale The boundary layer approximation, (omit prime and bar as Raynold average)

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left(\nu_t \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\nu_t \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) \quad (2.71)$$

ignore u_x, v, w and x, y turbulent diffusion, become

$$\frac{\partial u}{\partial t} = -\underbrace{\frac{1}{\rho_0} \frac{\partial p}{\partial x}}_{f(t)} + \frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) \quad (2.72)$$

Assume flow is forced by pressure, compare importance of other 2 terms, $u \sim U_0, t \sim T, z \sim H$

$$\frac{\text{Unsteadiness}}{\text{Turbulent Stress}} \approx \frac{U_0/T}{\nu_t U_0/H^2} = \frac{H^2}{\nu_t T} = \frac{H^2 \nu_t}{T} = \frac{T_{mix}}{T} \quad (2.73)$$

T is forcing timescale. $T_{mix} = H^2/\nu_t$ is the time it takes for momentum to be mixed over distance H .

case (1) $T_{mix} \gg T$, unsteadiness much larger than viscous,

$$\Rightarrow \frac{\partial u}{\partial t} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} = f(t) \quad (2.74)$$

oscillatory tidal forcing

$$-\frac{1}{\rho_0} \frac{\partial p}{\partial x} = P_x \cos(\omega t) \quad \omega = \frac{2\pi}{T} \quad T = 12.4 \text{ hr} \quad (2.75)$$

$$\frac{\partial u}{\partial t} = P_x \cos(\omega t) \Rightarrow u(t) = \frac{P_x}{\omega} \sin(\omega t) \neq f(z) \quad (2.76)$$

case (2) $T_{mix} \ll T$, viscous much larger than unsteady

$$0 = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) \quad (2.77)$$

Solid bottom boundary $z = 0, u = 0$, no stress condition at $z = H, \frac{\partial u}{\partial z} = 0$. If $\nu_t = \text{const}$, integrate and get

$$u(z, t) = A(t)(z^2 - 2Hz) \quad A(t) = -\frac{1}{2\nu_t} \frac{1}{\rho_0} \frac{\partial p}{\partial x} = \frac{1}{2} P_x \cos(\omega t) \quad (2.78)$$

When $T_{mix} \gg T, H^2 \gg \nu_t T$, which shows deep case. On the contrary, shows shallow case. In the deep case, the flow goes $\sin(\omega t)$ while forcing goes $\cos(\omega t)$, flow lags forcing. This reflects effects of inertia of flow. In the shallow case, the flow goes $\cos(\omega t)$ while Forcing goes with $\cos(\omega t)$, means there is no inertia and flow evolves with forcing.

When baroclinic
 $f(t) \rightarrow f(z, t)$.

short for turbulent
viscous

Costal Embayment Channel-Shoal Morphology Deep part have larger inertia.

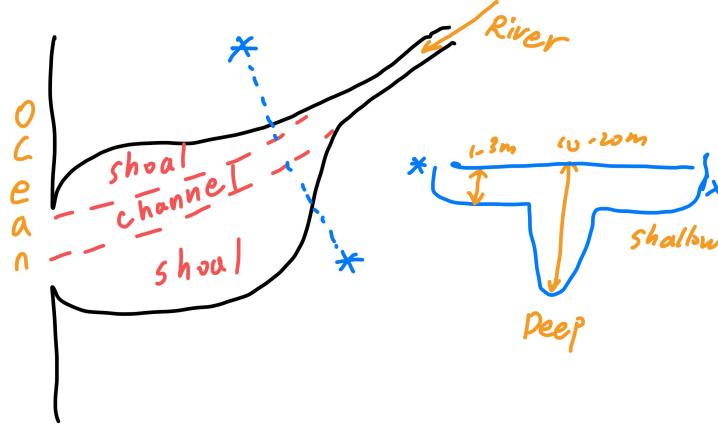


Figure 6: Costal Embayment

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \nu_t \frac{\partial^2 u}{\partial z^2} \quad (2.79)$$

$u(0, t) = u_0 \cos(\omega t)$, infinite plate $\frac{\partial p}{\partial x} = 0$. Periodic steady state solution. Solution of the from $u(z, t) = e^{i\omega t} f(z)$ and take the real part.

$$i\omega e^{i\omega t} f = \nu_t e^{i\omega t} f'' \Rightarrow f'' - \frac{i\omega}{\nu_t} f = 0 \quad (2.80)$$

$$k = \pm(i + 1) \sqrt{\frac{\omega}{2\nu_t}} \quad f(z) = Ae^{kz} + Be^{-kz} \quad (2.81)$$

To prevent $f \rightarrow \infty$ as $z \rightarrow \infty$, $B = 0$.

$$u(z, t) = u_0 e^{i\omega t} e^{-(1+i)z\sqrt{\omega/2\nu_t}} = u_0 e^{-z\sqrt{\omega/2\nu_t}} e^{i(\omega t - z\sqrt{\omega/2\nu t})} \quad (2.82)$$

Take real part,

$$u(z, t) = u_0 e^{-z\sqrt{\omega/2\nu_t}} \cos\left(\omega t - \sqrt{\frac{\omega}{2\nu_t}} z\right) \quad (2.83)$$

vertical structure set by $\phi(z) = z\sqrt{\omega/2\nu_t} = \sqrt{\pi}\sqrt{z^2/\nu_t T}$. Note this is similar with $H^2/\nu_t T$.

2.8 Stratified TKE Equation And Richardson Number

TKE equation

$$\frac{\partial q^2}{\partial t} + u_j \frac{\partial q^2}{\partial x_j} = \frac{\partial}{\partial x_j} \left(k_q \frac{\partial q^2}{\partial x_j} \right) + 2P - 2\epsilon \quad (2.84)$$

If we allow $\rho = \bar{\rho} + \rho'$, in Boussinesq approximation, ρ' only appears in $\rho' g$ in w' equation.

$$\frac{\partial w'}{\partial t} + \dots = \dots - \frac{\rho'}{\rho_0} g \Rightarrow \frac{\partial}{\partial t} (\overline{w'^2}/2) + \dots = \dots - \frac{g}{\rho_0} \overline{\rho' w'} \quad (2.85)$$

so we can add it to the TKE equaiton

$$\frac{\partial q^2}{\partial t} + u_j \frac{\partial q^2}{\partial x_j} = \frac{\partial}{\partial x_j} \left(k_q \frac{\partial q^2}{\partial x_j} \right) + 2P + 2B - 2\epsilon \quad 2B = -\frac{2g}{\rho_0} \overline{\rho' w'} \quad (2.86)$$

B is Buoyancy “production”.

Since $\bar{\rho}'w' = -k_\rho \frac{\partial \bar{\rho}}{\partial z}$, Then if in stable stratification case, $\frac{\partial \bar{\rho}}{\partial z} < 0$, then $\bar{\rho}'w' > 0$, $B < 0$ is a sink of energy. On the other hand, if the profile is unstable at first, the term serves as a source for TKE, and there will be overturning and potential energy is transforming into kinetic energy. Usually only $B < 0$ case persist in the environment.

For a case where there is both velocity profile $\bar{u}(z)$ and stable stratification $\bar{\rho}(z)$, B and shear production P will compete. On the other hand, turbulence will decrease both the shear and stratification strength. So in order to maintain a steady state, there should exist outer forcing. For shear it can be the boundary, for stratification it can be temperature or salinity.

Richardson Numbers Capture the competition between shear and stable stratification.

Gradient Richardson Number

$$Ri_g = \frac{N^2}{\left(\frac{\partial u}{\partial z}\right)^2} = \frac{-\frac{g}{\rho_0} \frac{\partial \rho}{\partial z}}{\left(\frac{\partial u}{\partial z}\right)^2} \quad (2.87)$$

Ri_g large ($> 1/4$, approx.) leads to decaying turbulence. Ri_g small leads to active turbulence.

Munk-Anderson Turbulence model for stratified flows. Estimate ν_t, k_t , based on unstratified scaling first,

$$\nu_t^o = k_t^o = ku_* H \frac{2}{H} \cdot \left(1 - \frac{2}{H}\right) \quad (2.88)$$

And correct with Richardson number

$$\nu_t = \nu_t^o f(Ri_g) \quad k_t = k_t^o f(Ri_g) \quad (2.89)$$

the function f should start at 1 when $Ri_g = 0$ as be consistent with no-stratification case, and reach to 0 when $Ri_g \rightarrow \infty$. The choice is

$$f(Ri_g) = (1 + 10Ri_g)^{1/2} \quad (2.90)$$

conversion to potential energy due to mixing of $\bar{\rho}(z)$

Bulk Richardson Number

$$\frac{\partial \rho}{\partial z} \sim \frac{\Delta \rho}{H} \quad \frac{\partial u}{\partial z} \sim \frac{\Delta u}{H} \quad Ri_b = \frac{-\frac{g}{\rho_0} \Delta \rho H}{\Delta u^2} \quad (2.91)$$

Flux Richardson Number Compare the magnitude of the buoyancy flux due to turbulence $\bar{\rho}'w'$ and momentum flux $P = -u'w' \frac{\partial u}{\partial z}$.

$$R_f = \frac{-B}{P} \quad (2.92)$$

So $R_f > 0$ in stable stratification. Consider a case, steady, homogeneous turbulence.

$$P + B - \epsilon = 0 \quad \Rightarrow \quad P = \epsilon - B \quad (2.93)$$

Params are chosen from empirical ocean observation data.

P is a source and $\epsilon, -B$ is sink. So that shows $R_f \leq 1$ in all cases. $B = -R_f \cdot P$, observations in thermocline of ocean indicates $R_f = 0.15$; Numerical studies show $R_f = 0.15$ is maximum. That shows for much strongly stratified and less strongly stratified case, R_f is much lower.

$\epsilon = (1 - R_f)P$ means $\epsilon \approx (0.85 \sim 1.0)P$ and $B \approx (0 \sim 0.15)P$.

Oceanographic observations are able to get $\epsilon(z), T(z)$, then can infer $\bar{\rho}(z) \rightarrow N^2(z)$. As $B = -k_\rho N^2$, $k_\rho = -B/N^2$. So if we get B and N^2 we can get k_ρ . For $P + B = \epsilon$, we get $\epsilon = (-R_f^{-1} + 1)B$. So

$$k_\rho = \frac{R_f}{1 + R_f} \frac{\epsilon}{N^2} \quad (2.94)$$

homogenous leads to no advection and diffusion term in TKE equation

2.9 Water Column Model

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) \quad \frac{\partial C}{\partial t} = \frac{\partial}{\partial z} \left(k_t \frac{\partial C}{\partial z} \right) \quad (2.95)$$

$$\frac{\partial q^2}{\partial t} = \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) + 2P + 2B - 2\epsilon \quad (2.96)$$

Vertical Diffusion(viscosity) terms are implicit.

$$\frac{C_i^{n+1} - C_i^n}{\Delta t} = \frac{1}{\Delta z} \left[\left(k_t \frac{\partial C}{\partial z} \right)_{i+\frac{1}{2}}^{n+1} - \left(k_t \frac{\partial C}{\partial z} \right)_{i-\frac{1}{2}}^{n+1} \right] \quad (2.97)$$

$$\left[-\frac{\Delta t}{\Delta z^2} k_{t,i+\frac{1}{2}}^n \right] C_{i+1}^{n+1} + \left[1 + \frac{\Delta t}{\Delta z^2} (k_{t,i+\frac{1}{2}}^n + k_{t,i-\frac{1}{2}}^n) \right] C_i^{n+1} + \left[\frac{\Delta t}{\Delta z^2} k_{t,i-\frac{1}{2}}^n \right] C_{i-1}^{n+1} = C_i^n \quad (2.98)$$

While $k_{t,i+\frac{1}{2}}$ and $k_{t,i-\frac{1}{2}}$ is calc as following

$$k_{t,i+\frac{1}{2}}^n = \frac{1}{2}(k_{t,i}^n + k_{t,i+1}^n) \quad k_{t,i-\frac{1}{2}}^n = \frac{1}{2}(k_{t,i}^n + k_{t,i-1}^n) \quad (2.99)$$

For momentum form, the *lhs* is similar.

$$\left[-\frac{\Delta t}{\Delta z^2} \nu_{t,i+\frac{1}{2}}^n \right] u_{i+1}^{n+1} + \left[1 + \frac{\Delta t}{\Delta z^2} (\nu_{t,i+\frac{1}{2}}^n + \nu_{t,i-\frac{1}{2}}^n) \right] u_i^{n+1} + \left[-\frac{\Delta t}{\Delta z^2} \nu_{t,i-\frac{1}{2}}^n \right] u_{i-1}^{n+1} = u_i^n - P_{x_i}^n \Delta t \quad (2.100)$$

While the pressure term is

$$P_{x_i}^n = \left[-\frac{1}{\rho_0} \frac{\partial p}{\partial x} \right] (z_1, t_n) \quad (2.101)$$

Top Boundary $z = H$, $i = N$, $\frac{\partial u}{\partial z} = 0$, $u_{N+1} = u_N$. For $i = N$, it leads to

$$\left[1 + \frac{\Delta t}{\Delta z^2} \nu_{t,N-\frac{1}{2}}^n \right] u_N^{n+1} + \left[-\frac{\Delta t}{\Delta z^2} \nu_{t,N-\frac{1}{2}}^n \right] u_{N-1}^{n+1} \quad (2.102)$$

Bottom Boundary $z = 0$, $i = 0$, $\frac{\partial u}{\partial z} = \frac{u_*}{kz}$ comes from log-layer below $i = 1$.

Assume below $i = 1$ there is log profile.

$$\frac{u_1 - u_0}{\Delta z} = \frac{u_*}{\kappa \Delta z} \Rightarrow u_0 = u_1 - \frac{u_*}{\kappa} \quad (2.103) \quad u(z) = \frac{u_*}{k} \ln \frac{z}{z_0}$$

$$\frac{u_1^{n+1} - u_1^n}{\Delta t} = -P_{x1}^n + \frac{1}{\Delta z} \left[\nu_{t,\frac{3}{2}} \frac{\partial u}{\partial z} \Big|_{\frac{3}{2}} - \nu_{t,\frac{1}{2}} \frac{\partial u}{\partial z} \Big|_{\frac{1}{2}} \right] \quad (2.104)$$

with $u_*^2 = C_d u_1^2$, above eq turns into

$$u_1^{n+1} = u_1^n - \Delta t \cdot P_{x1}^n + \frac{\Delta t}{\Delta z^2} \left[\nu_{t,\frac{3}{2}}^n (u_2^{n+1} - u_1^{n+1}) - \nu_{t,\frac{1}{2}}^n \frac{C_d^{1/2}}{\kappa} u_1^{n+1} \right] \quad (2.105)$$

which leads to

$$\left[-\frac{\Delta t}{\Delta z^2} \nu_{t,\frac{3}{2}}^n \right] u_2^{n+1} + \left[1 + \frac{\Delta t}{\Delta z^2} \nu_{t,\frac{3}{2}}^n + \frac{\Delta t}{\Delta z^2} \frac{\sqrt{C_d}}{\kappa} \nu_{t,\frac{1}{2}}^n \right] u_1^{n+1} = u_1^n - P_{x1}^n \quad (2.106)$$

For P, B, ϵ terms, explicitly calculate

$$P_i^n = - \left[\overline{w'w'} \frac{\partial u}{\partial z} \right]_i^n = \nu_{t_i}^n \left[\frac{u_{i+1}^n - u_{i-1}^n}{2\Delta z} \right]^2 \quad (2.107)$$

$$B_i^n = -\frac{g}{\rho_0} \overline{w'\rho'} = k_\rho \left(-\frac{g}{\rho_0} \frac{\partial \rho}{\partial z} \right) = [k_\rho N^2]_i^n \quad (2.108)$$

$$\epsilon \approx \frac{(q^2)^{3/2}}{l} \quad \epsilon_i^n = \left[\frac{(q^2)^{3/2}}{B_1 l} \right]_i^n \quad B_1 = 15 \sim 16 \quad (2.109)$$

So the mixed explicit-implicit formulation for ϵ

$$\frac{q_i^{2,n+1} - q_i^{2,n}}{\Delta t} = [\text{Diff}]_i^{n+1} + 2P_i^n + 2B_i^n - \left[\frac{2\sqrt{q^2}}{B_1 l} \right]_i^n \cdot q_i^{2,n+1} \quad (2.110)$$

Code Blocking

1. Advance $u_i^n \rightarrow u_i^{n+1}$, uses $\nu_{t_i}^n, P_{x_i}^n$. $u_{p_i} \rightarrow u_i$
2. Advance $C_i^n \rightarrow C_i^{n+1}$, uses $\kappa_{z_i}^n$. $C_{p_i} \rightarrow C_i$
3. Advance $q_i^{2,n}, q^2 l_i^n \rightarrow q_i^{2,n+1}, q^2 l_i^{n+1}$, uses $\kappa_{q_i}^n, \kappa_{z_i}^n, \nu_{t_i}^n, u_i^n, N_i^{2,n}$. $Q2_{p_i} \rightarrow Q2_i$
4. Update everything

$$L_i^{n+1} = \frac{Q2L_i^{n+1}}{Q2_i^{n+1}} \quad Q_i^{n+1} = \sqrt{Q2_i^{n+1}} \quad (2.111)$$

$$\nu_{t_i}^{n+1} = S_m Q_i^{n+1} L_i^{n+1} \quad k_{z_i}^{n+1} = S_h Q_i^{n+1} L_i^{n+1} \quad k_{q_i}^{n+1} = S_q Q_i^{n+1} L_i^{n+1} \quad (2.112)$$

S_m, S_h, S_q are all empirical coefficients.

5. $F_p = F$ for all variables.

Steady Turbulent Channel Flow

$$0 = -\frac{1}{\rho} \frac{\partial P}{\partial x} + \frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) \quad (2.113)$$

$$0 = \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2}{\partial z} \right) + 2P - 2\epsilon \quad (2.114)$$

$$0 = \frac{\partial}{\partial z} \left(k_q \frac{\partial q^2 l}{\partial z} \right) + 2Pl - 2\epsilon l \quad (2.115)$$

This is unable to solve analytically. We can only use time advancement to let flow evolve to steady state. Define a convergence threshold, and define

$$C_u = \sum_{i=1}^N (u_i^{n+1} - u_i^n)^2 < \text{threshold for convergence} \quad (2.116)$$

2.10 Vegetated Flows

Vegetated flows, in wetlands, marshes ... there is drag force on the flow.

Vegetation drag force, when flow around a cylinder,

$$F_D = C_D \cdot \frac{1}{2} \rho u^2 A_p \quad (2.117)$$

so

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x} + \frac{\partial}{\partial z} \left(\nu_t \frac{\partial u}{\partial z} \right) - \frac{F_D}{\rho(\Delta V)} = \dots - \underbrace{\frac{C_D A_p}{2\Delta V} u^2}_{C_{veg}} \quad (2.118)$$